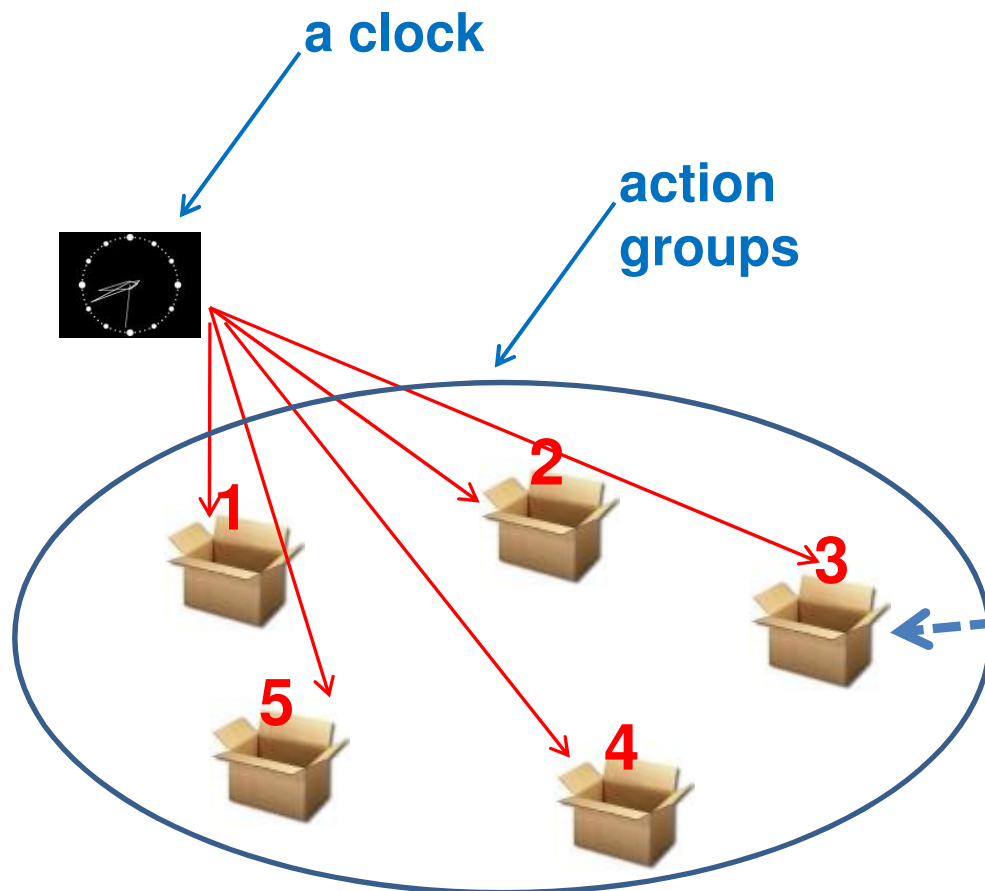

Pietro Terna - DipEco

2. Schedule



What in each box?

Tasks to be executed (with $p=1$ or with $p<1$)

Tasks are included into the code in a static way, or can be added/activated dynamically by other tasks, also via agents' actions

Tasks can be read – via a 'read' task schedule element – from an external source (file, web interaction, ...)

A special type of task to be read from an external source is that of the **recipes**

tasks read from an external archive

a_n – a specific agent (instance of class A)

a_X – a randomly chosen agent (instance of class A)

a_%all – a quota of all the agents (instances) of the class A

a_all – all the agents (instances) of the class A



[agent method]

methods specific of each agent or
inherited
from the basic type 'agent'

recipes read from an external archive


Recipes as a whole
have an id or name

[[agent method] [agent method] [agent method] [agent method] [agent method] ...]

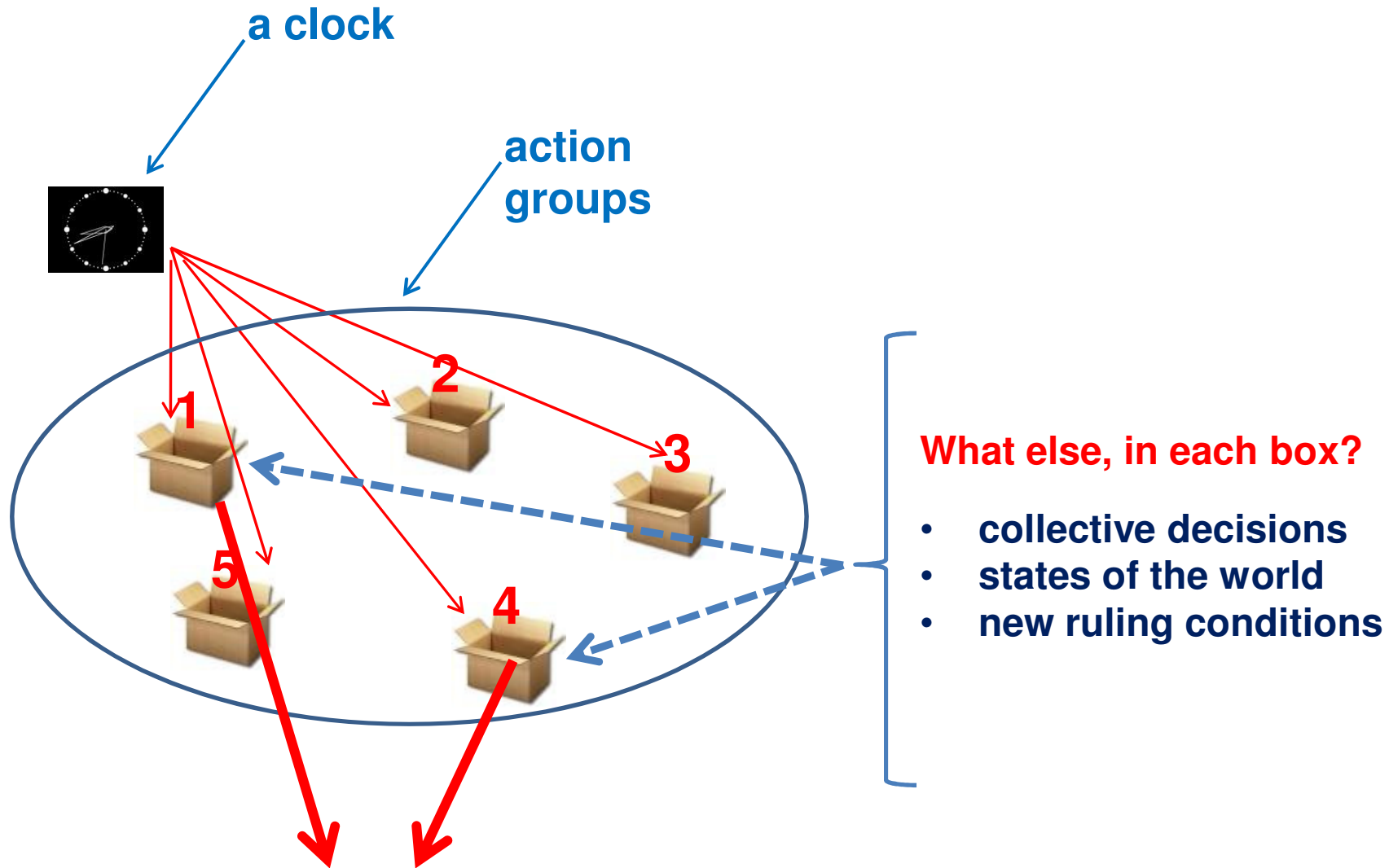
→ to be executed in a sequential way by a given thread of agents
(static or dynamic)

[[agent method] **[[agent method] [agent method] [agent method]]** [agent method] ...]

with segments to be executed in a parallel way

[[agent method] [agent method] **N**[agent method] [agent method] [agent method] ...]
[.....  :: [agent method]]
[..... ::]
[..... [agent method]]

with components belonging to different recipes to be executed as a whole



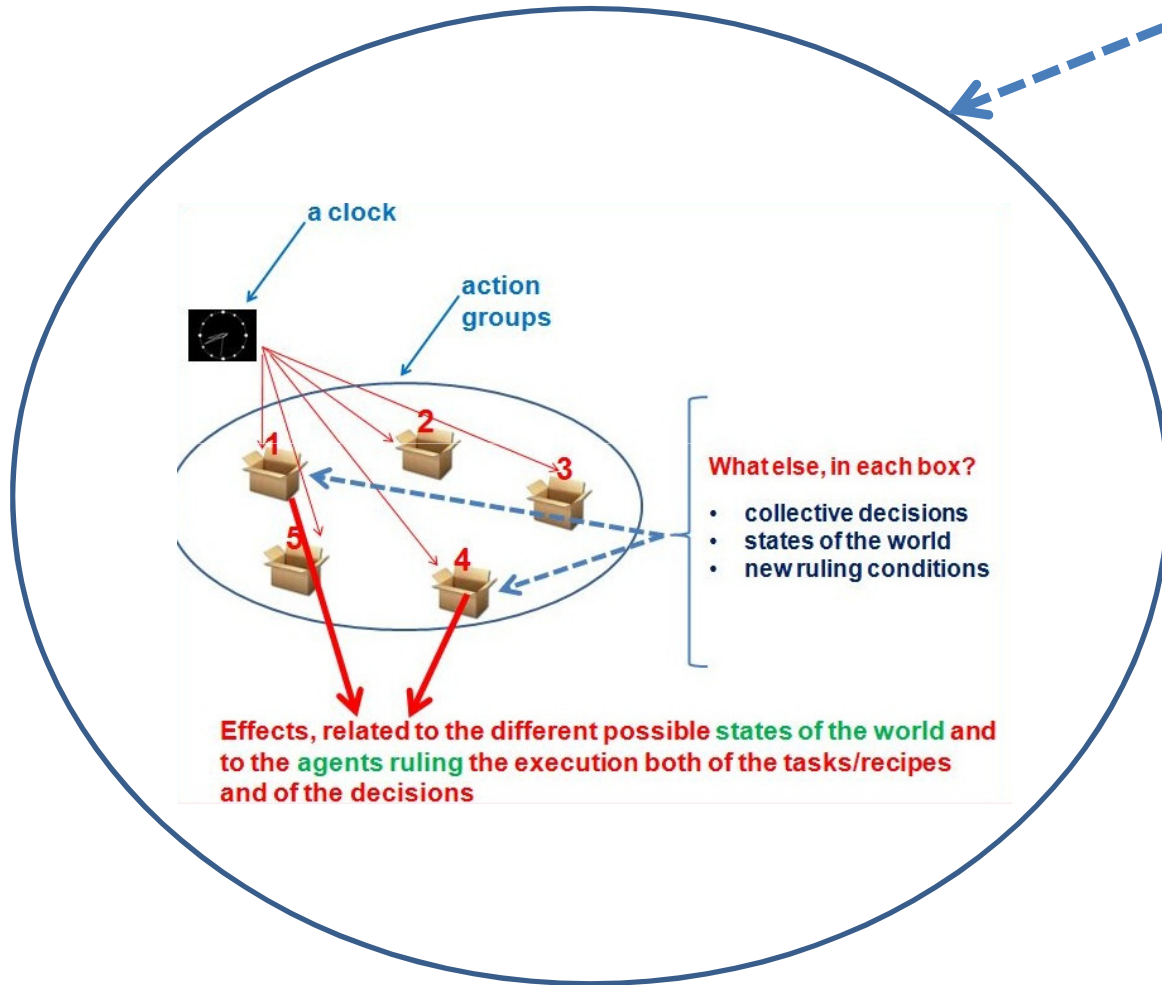
Effects, related to the different possible states of the world and to the agents ruling the execution both of the tasks/recipes and of the decisions

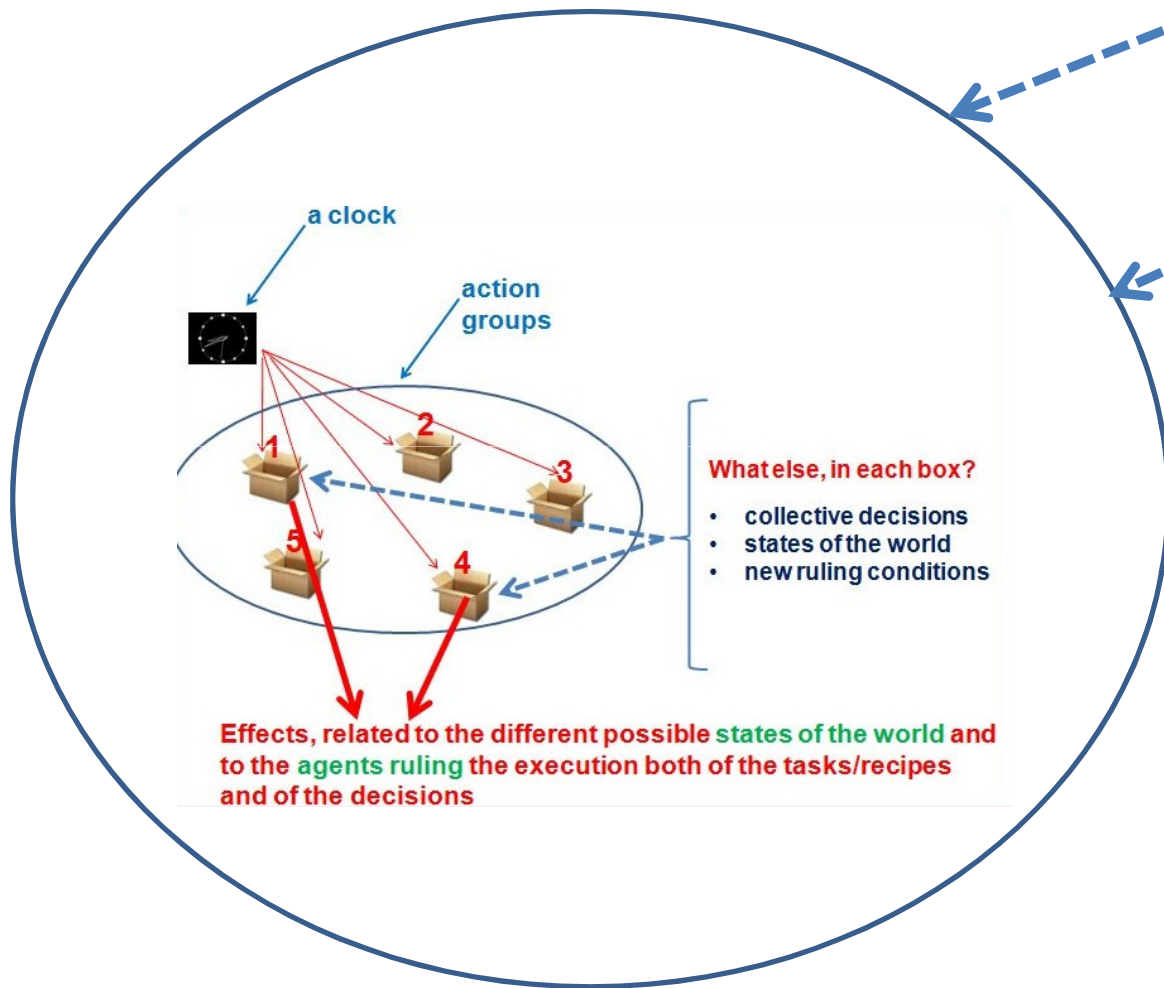
repeated trial and error processes

with

reinforcement learning and NN to memorize and apply the outcomes

NN directly trained via a trial and error process (guessing actions and effects)





Will **valid rules** emerge?

Will **anarchists*** help to improve that kind of emergence?

(*) randomly acting agents