

An aerial view of a city with a river. The city is represented by a grid of buildings, and numerous colorful markers (red, green, blue, yellow, purple) are scattered across the city, representing agents in a simulation. The river is a prominent blue feature winding through the city.

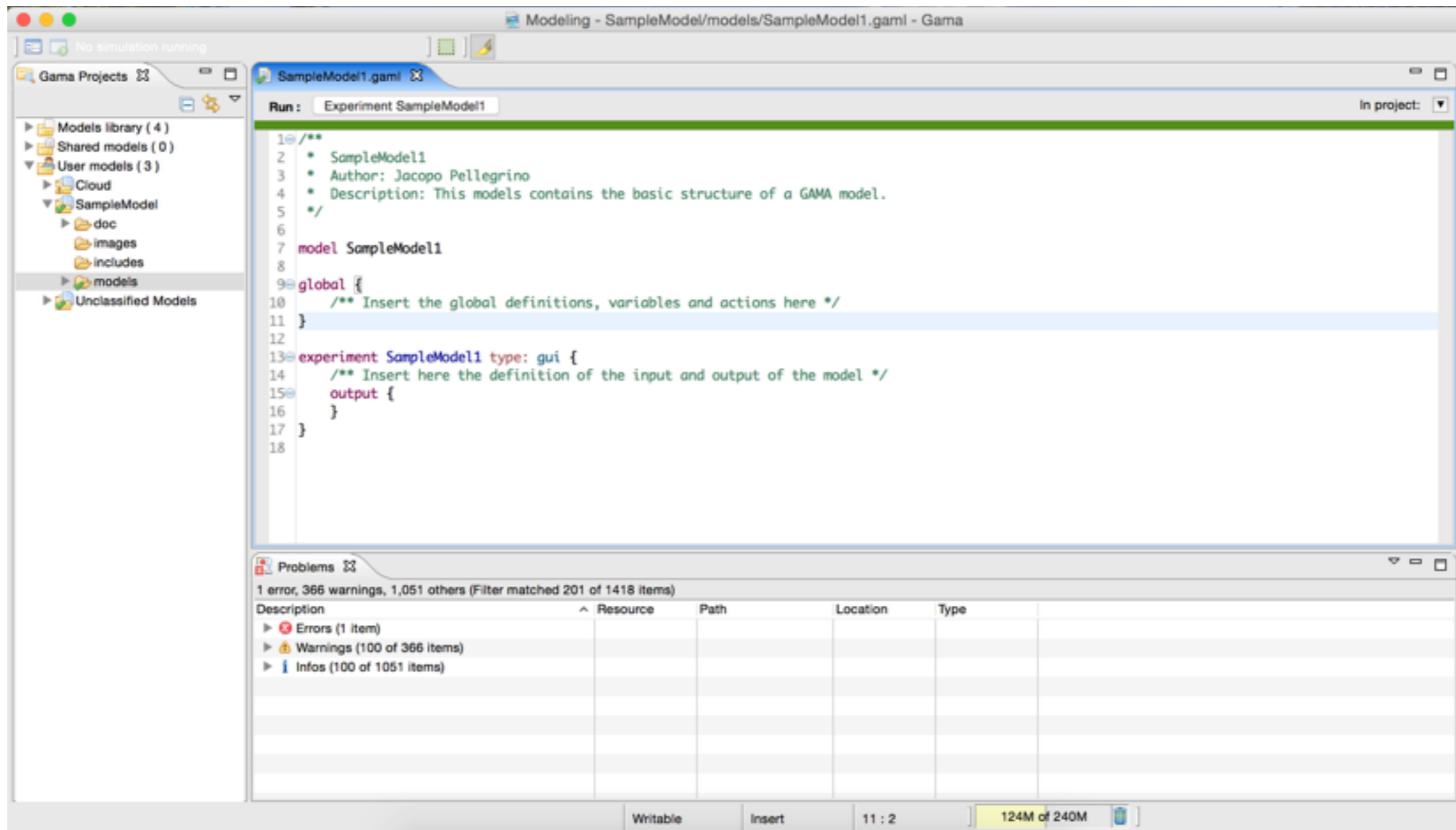
# GAMA

*Gis & Agent-based Modeling Architecture*

# Introduction

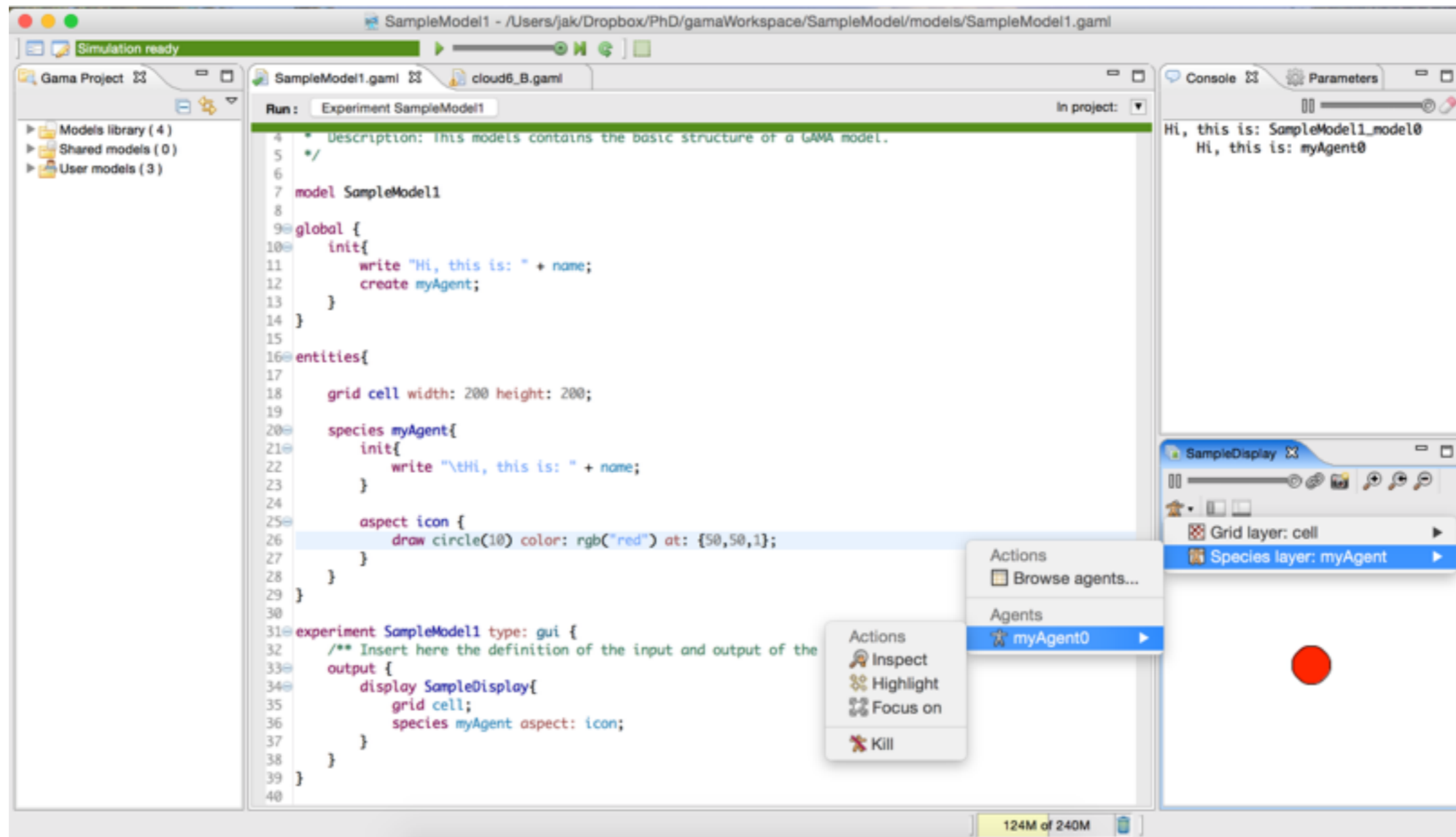
- Gis & Agent-based Modeling Architecture
- Agent-based, spatially explicit, modeling and simulation platform.
- Free and Open Source tool (GAMA webpage).
- Initially developed as an Eclipse plug-in, now is an independent tool.
- GAML (Gis & Agent-based Modeling Language) agent-oriented language, close to Java.
- Instantiation of agents from any kind of dataset, including Gis data (e.g.: road traffic model).

# Features



Modeling perspective

# Features



Simulation perspective

# Modeling Introduction

Model file made up of three main parts:

- **global**

- Variables, constants that must be **accessible to every agent at any time** during the simulation.
- Initialization, reflexes, actions that are **common to every species** in the model.

- **entities**

- Definition of spatial environment (**grid**).
- Definition of **species** and their **skills, actions** and **reflexes**.

- **experiment**

- Possibility to display world and agents.
- Several options for plotting data (charts, histograms, etc.).

# Species Relationship

Species can be related to each other:

- **Nesting:** a species can be defined within another one. The enclosing one is referred as *macro species*, the enclosed one as *micro species*.
- **Inheritance:** a *child* species extends behavior from the *parent*, close to what happens in Java.

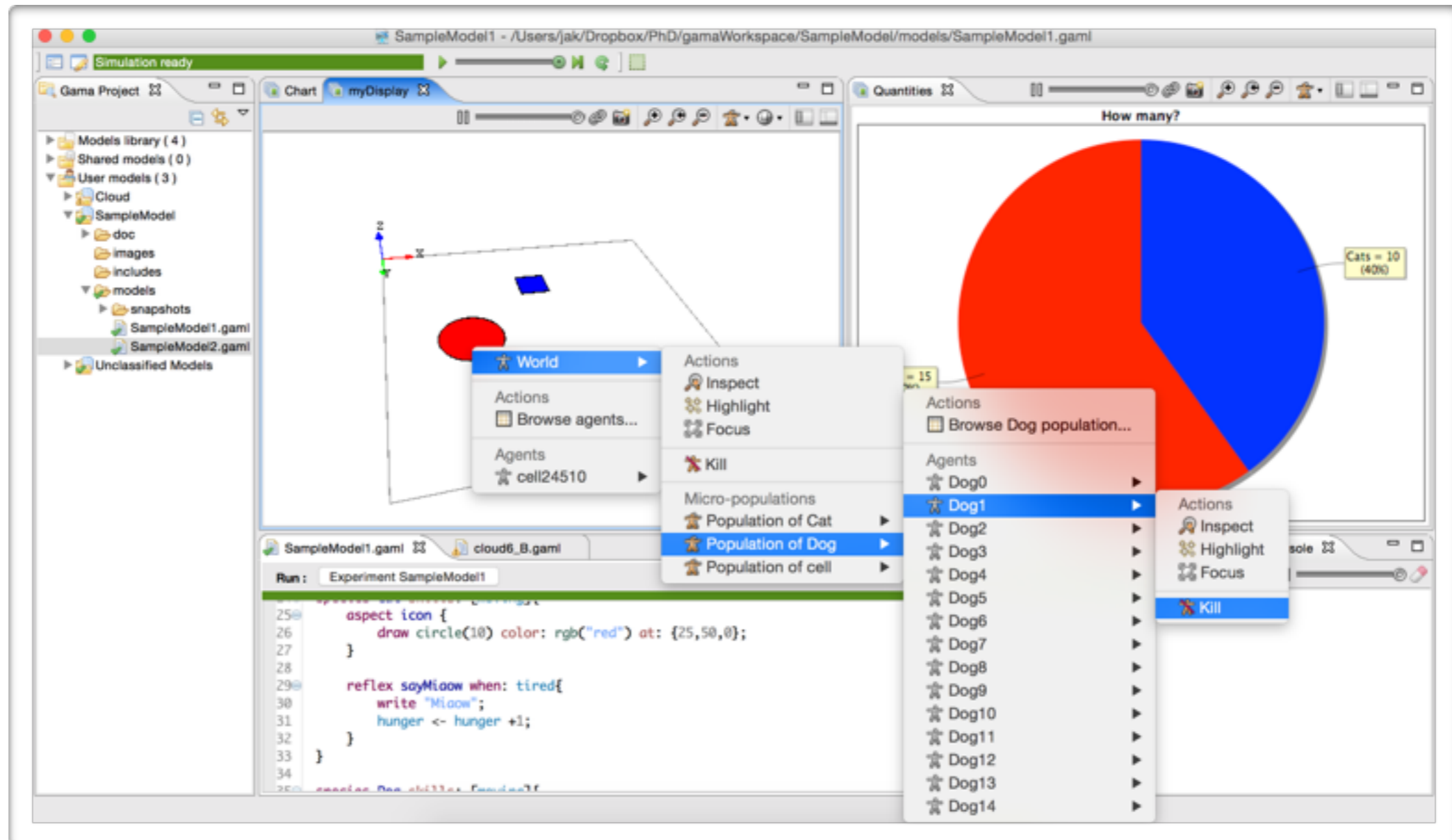
# Agent Monitoring

It is possible to monitor agents:

- Agent Browser: browse population of agent species, highlight one, monitor a species.
- Agent Inspector: retrieve information related to one or more specific agent(s), e.g. position, speed, internal variables and the like.

# Agent Monitoring

## Agent Browser





# Data input and output

Data I/O:

- Data can be imported and exported in and from the model.
- Data can be exported by means of the **save** command.
- Several common formats can be read in: .txt, .csv, .png, etc.
- The destination path must refer to an **existing folder**, otherwise an error arises.

# Introduction



# Modeling

In the following we will take a closer look to the implementation of a MAS in GAMA focusing on:

- The GAML language (structures, operators, etc.).
- The display of agents and data.
- The FIPA communication protocol.

Further information can be found in the documentation.

# GAML - Variables

Variables Definition:

- Variables are **declared** with the following syntax:

```
datatype var_name [optional_attributes];
```

```
int myVar update: myVar + 1;
```

- If not **initialized** they get default values. To initialize:

```
datatype var_name <- value [optional_attributes];
```

```
int myVar <- 5 update: myVar + 1;
```

Variables name must not begin with a white space or digit, by convention it should be a lower case letter.

# GAML - Actions

Actions Definition:

- An action embodies a **capability of an agent**, it can take from 0 to many arguments and return 0 or one variable. It is declared as follows:

```
action noArgNoReturn{  
}  
action noArgReturn{  
  return returnVar;  
}  
action argNoReturn(type1 arg1, type2 arg2){  
}
```

- It is possible to assign a return variable directly to a variables as follows:

```
int myVar <- argReturn(arg1::val1, arg2::"val2");
```

# GAML - Reflexes

Reflexes Definition:

- A reflex can be considered as an action that the **agent automatically performs** at any time step or when a given condition occurs. In reflexes action can be called. A reflex is defined as follows:

```
reflex everyTime{
    //is executed at every time step
}
reflex someTimes when: booleanExpression{
    //is executed only when the boolean expression is true
}
action argNoReturn(type1 arg1, type2 arg2){
}
```

- The `init` is a special kind of reflex that is executed when the agent is created.

# GAML - Loops

It is possible to create a *for loop* (iterating a variable between two values) with the following statement:

```
loop i from: minVal to: maxVal { ... }
```

- The code between { ... } is executed  $\text{maxVal} - \text{minVal}$  times, the increasing statement is implicit.

```
loop i from: 0 to: length(temp_files) - 1 {  
  write temp_files[i];  
}
```

- Pay attention to the out-of-bound error. 

# GAML - If / Else

If / Else statement syntax:

```
if booleanCondition {  
    //code to be executed if true  
} else{  
    //code to be executed if false  
}
```

- The compiler does not check the boolean condition, the following code will generate a run time error.

```
if 0 {  
    //this is a bad written if statement  
}
```

- Use `flip(numBetween0and1)` to randomly generate true or false.



# GAML - Switch

- The `switch` statement allows to evaluate more combinations than the `if{}else{}.` The syntax is the following:

```
switch expression{
  match 1 { //if expression = 1
  }
  match_one [1, 2, 3] { //if expression = 1, 2 or 3
  }
  match_between [4, 6] { //if expression = 4, 5 or 6
  }
  default { //if expression is neither of them
  }
}
```

# GAML - Graphics

- A graphical representation can be useful in several modeling scenarios.
- GAMA allows the display of agents within an environment referred as the grid.
- Layers of agents can be displayed separately.
- The output of the experiments can be displayed too.

# GAML - Communication

- In GAMA the communication is based upon the FIPA Agent Communication Language.
- FIPA messages are labeled with a **performative** that specifies the type of message in terms of purpose.
- Thanks to the performatives it is possible to build **interaction protocols** (patterns of behavior).

- Example: 

```
reflex sendCFP when: (time = 1) {  
    loop p over: Participant{  
        do start_conversation with: [  
            receivers :: [p],  
            protocol :: 'fipa-cfp',  
            performative :: 'cfp',  
            content :: ['cont']  
        ];  
    }  
}
```

# Language and Communication

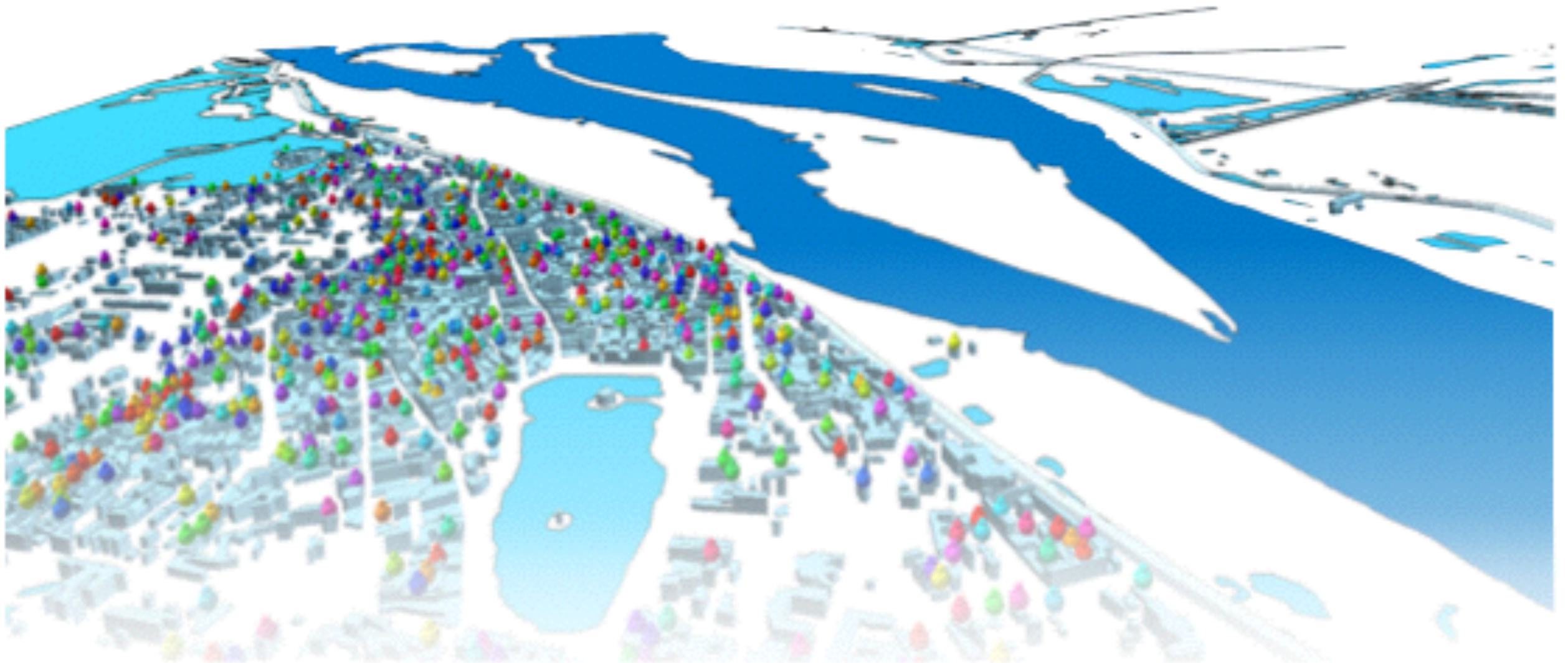


# Prey / Predator Model

The aim of this model is to simulate a natural environment in which two species of animals coexist.

- The environment is made up of a grid of cells representing the soil with grass.
- Preys look around for grass to eat.
- Predators look around for preys to eat.

# Thanks for the Attention



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